

L + Constraint(s)

A constraint $q_t + \sum_i a_i \dot{q}_i = 0 \quad \dots (*)$

EOM $-\frac{\partial L}{\partial q_i} + \frac{d}{dt} \frac{\partial L}{\partial \dot{q}_i} = a_i \lambda(t)$

(**) When using a $\lambda(t)$, a Lagrange undetermined multiplier, all q_i 's are considered as free variables before setting up EOM's.

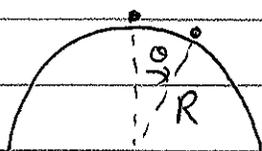
(***) After setting up EOM's, the constraint(s) can be used with EOM's to solve the problem. However, constraints should not be used before setting up EOM's, when dealing with them through $\lambda(t)$'s!!

* If there are multiple constraints then

$$a_i \lambda(t) \rightarrow \sum_k a_{i,k} \lambda_k(t)$$

$k \dots$ constraint index

Ex.) Bug-on-head problem



constraint : $r = R$

$\Rightarrow \dot{r} = 0 \quad \leftarrow \dots$ in the form of (*)!

$$L = \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\theta}^2) - mgr \cos \theta$$

$\Rightarrow a_t = 0, a_r = 1, a_\theta = 0$
comparing with (*)

EOM's : $-mr\dot{\theta}^2 + mg \cos \theta + m\ddot{r} = \lambda(t)$

$-mgr \sin \theta + \frac{d}{dt} (mr^2 \dot{\theta}) = 0$

not $r = R$!!

Because of (***)!!

Now, having obtained EOMs, we are free to use the constraint $r = R$, to set $\dot{r} = 0$

$\frac{d}{dt} (mr^2 \dot{\theta}) = mR^2 \ddot{\theta}$ (But not before setting up EOMs!)

$\therefore \lambda(t) = mg \cos \theta - mR \dot{\theta}^2$